

# Satellites for Digitalization Of Railways

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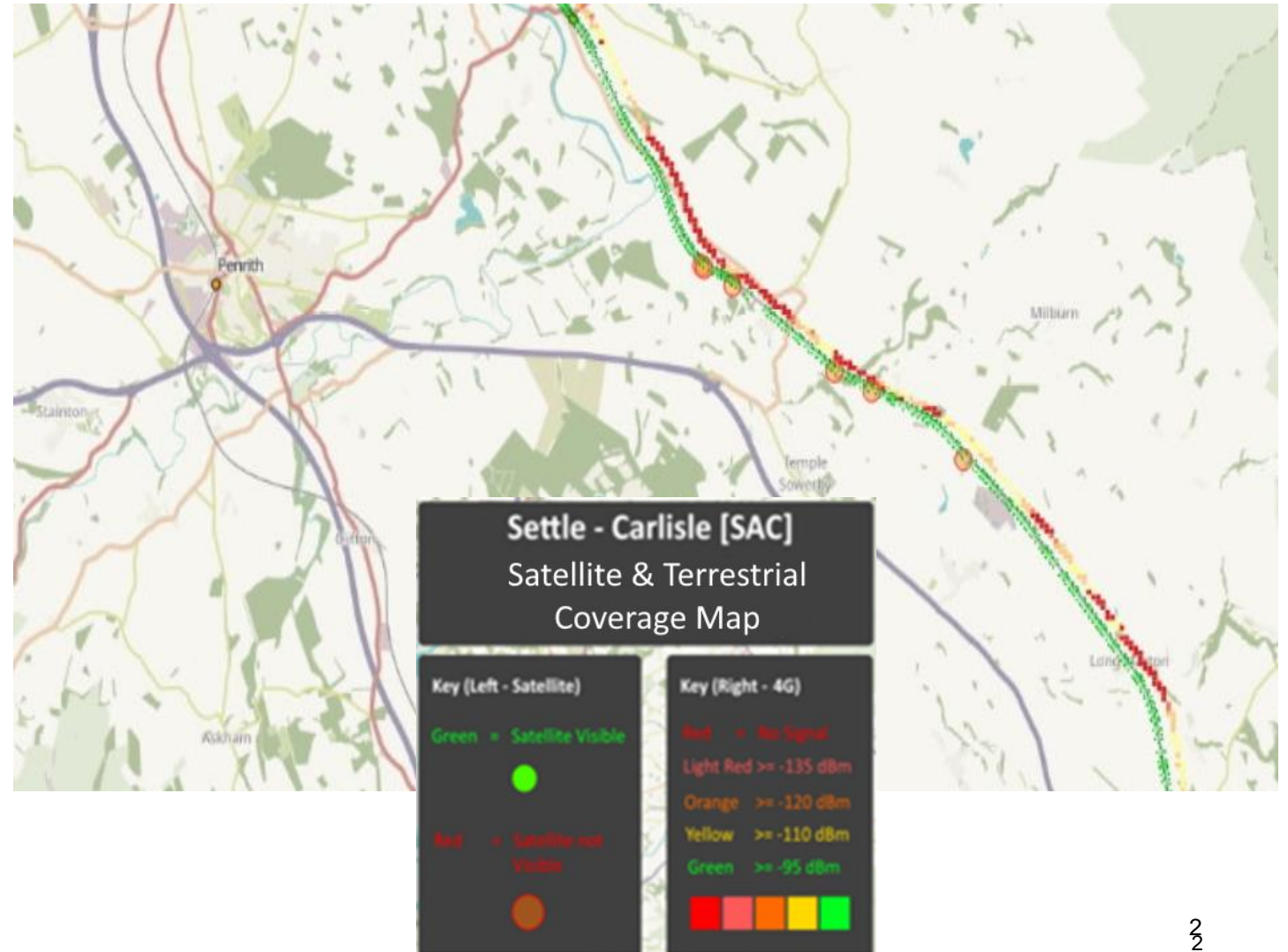
**CGI**



# What is SODOR?

‘The Satellites for Digitalisation of Railways’

- European Space Agency project led by CGI which aims to demonstrate the way new constellations of communication satellites can fill gaps in terrestrial coverage and provide additional capacity to improve safety and provide travellers with better connectivity.



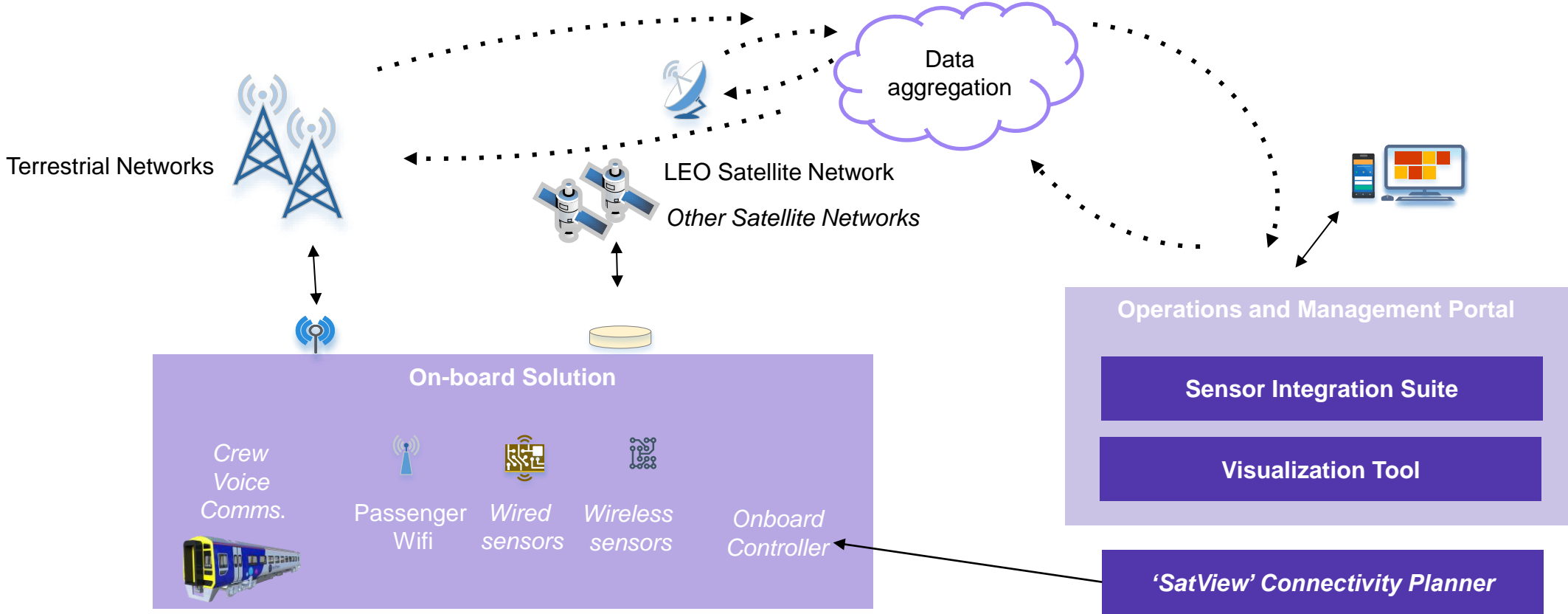
# SODOR project

- CGI are leading a consortium to develop a Proof Of Concept combining satellite and terrestrial networks
  - Partners include Network Rail and three UK Train Operating Companies
  - Successfully 1<sup>st</sup> demonstration of a rail-based HBR service (OneWeb) on North York Moors Railway in Oct '23



# SODOR Architecture

- The architecture is very flexible to specific customer needs with many optional components (shown in italics)
- CGI are supplier-agnostic and SODOR components are also designed to be able to integrate with other components from outside the current SODOR programme





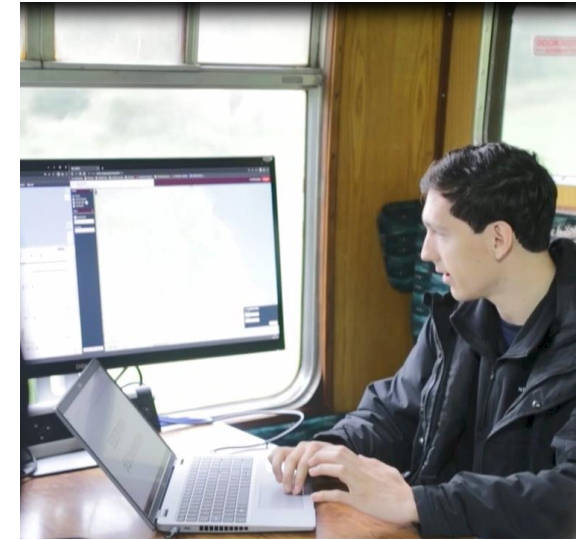
# North Yorks Moors Railway Trial

- North York Moors Railway is an excellent test environment with a demanding environment similar to rural operational railway lines and where it is more practical to do a longer period of testing
- The raft has been designed to allow testing the effectiveness of the SODOR solution on various lines without the requirement to undertake structural modifications of the trains
  - It has been designed to support multiple terminals and other equipment – only a small proportion of the space is actually being used for the equipment in the trial



# The Results

- In test runs, the satellite network achieved ~99% coverage. This compares to system based on terrestrial network coverage averaging around 60%.
- The Satellite network provided very good performance sufficient to provide good connectivity for >100 simulated active users
- Achieved 78 MBps downlink, 15 MBps uplink (max available on test package).
- Latency: Round trip time of 170ms, similar to terrestrial routing solutions in practice
- All this was achieved in poor weather conditions with frequent rain (sometimes very heavy) and cloud cover!



# Connectivity planning

LiDAR data used to analyse and identify hazards and blockages to line of sight for satellite communication paths

- Identify how much of the train route is visible
- Select best satellite to use for connectivity

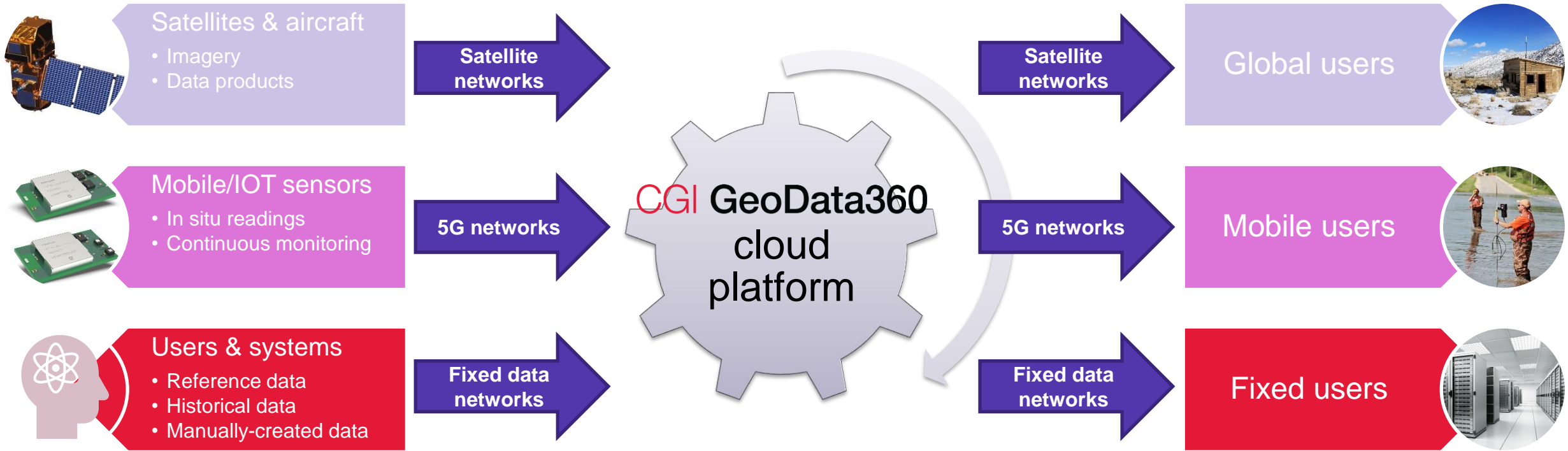
GeoData360 workflow analysis:

- Output in two formats
  - One for direct use by portal
  - One for display in eg QGIS



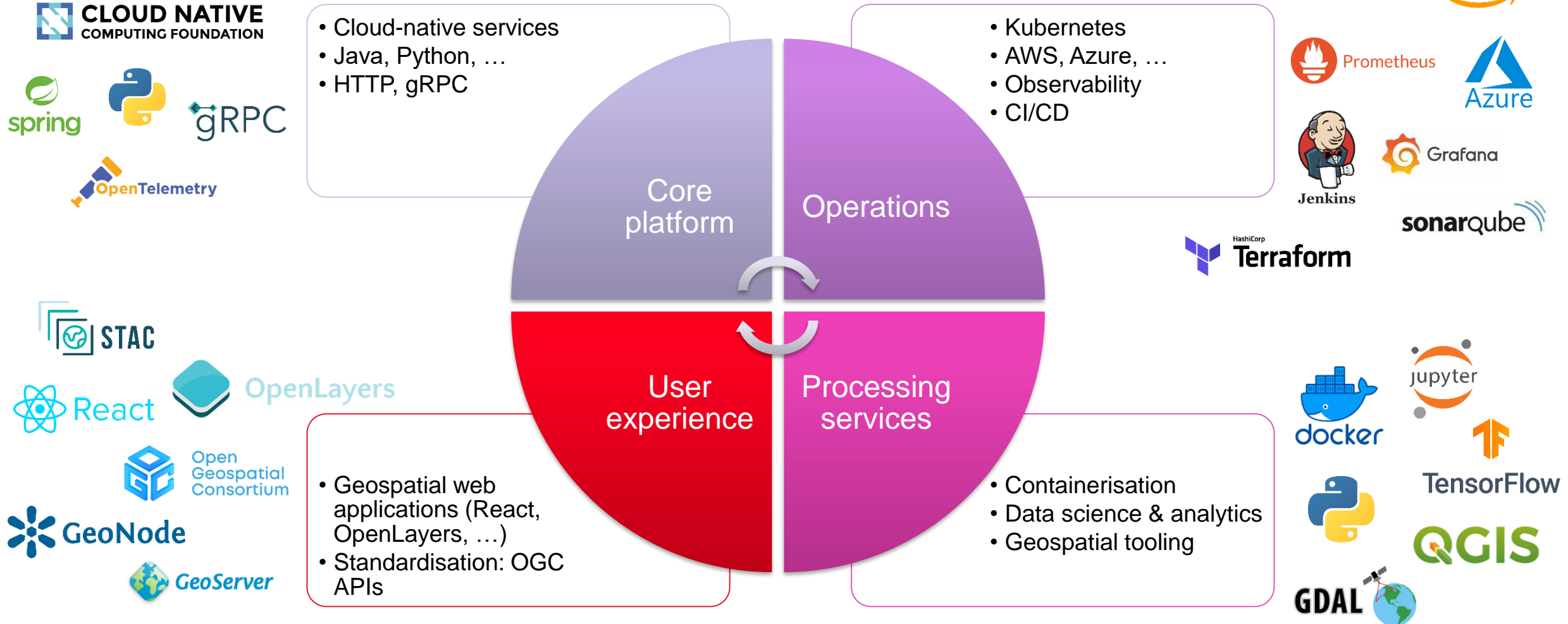


# GeoData360 data pipeline





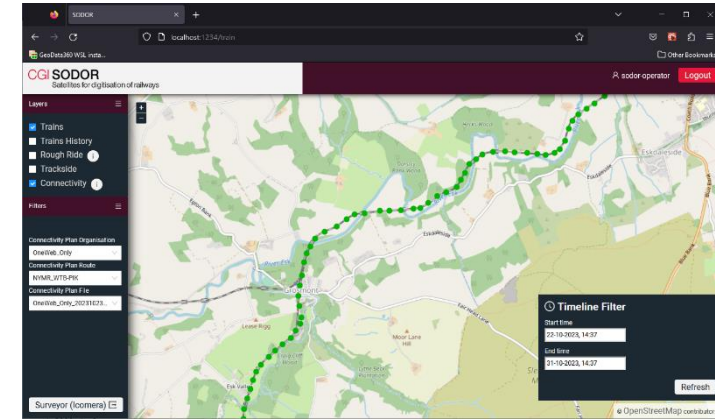
# GeoData360: Key technologies



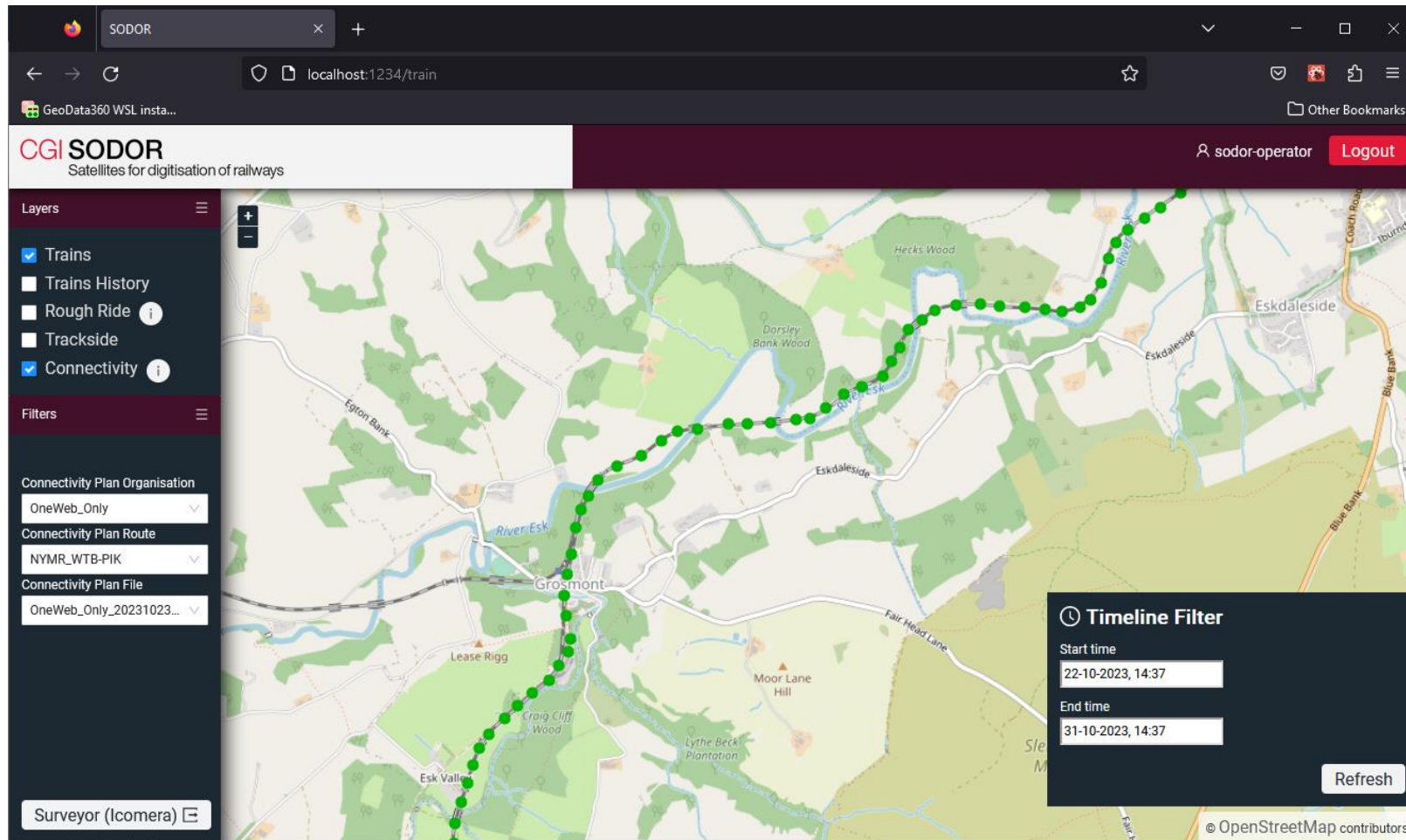
# Portal

Developed using:

- React
- OpenLayers
- Connects to a custom API written in Java
- Some endpoints backed by a PostgreSQL database
- Others come directly from SensorInsights360 (CGI product built on FOSS)



# Satellite Connectivity



# Displaying Rough Ride Events

The screenshot shows the SODOR web application interface. The browser address bar displays `https://sodor-staging.observing.earth/train`. The page header includes the SODOR logo and the text "Satellites for digitisation of railways", along with a user profile for "sodor-operator" and a "Logout" button.

On the left side, there is a sidebar with the following sections:

- Layers:** Trains (checked), Trains History (unchecked), Rough Ride (checked), Trackside (unchecked).
- Filters:** Comfort Score (Fairly Uncomfortable x, Uncomfortable x).
- Train Filter:** 1V01.
- Carriage Position Filter:** Device-C x.

The main map area shows a satellite view of a railway track with several red circular markers numbered 1 through 5. A popup window titled "Rough Ride Event" is open over marker 1, displaying the following data:

Device	Device-C
Train	1V01
Latitude	54.251002
Longitude	-0.777192
Speed	7.574 mph
Course	214.44 degrees
<hr/>	
Comfort ISO	0.806
Comfort ISO Level	Uncomfortable
Comfort BSI	2.214
<hr/>	
Sickness	0.021
Max acceleration time	2023-10-16 10:55:14
Max acceleration	14.976 m/s <sup>2</sup>
Max jerk time	2023-10-16 10:55:14
Max jerk	1315.805 m/s <sup>3</sup>

At the bottom right of the map, there is a "Timeline Filter" popup with the following settings:

- Start time: 14-10-2023, 10:52
- End time: 17-10-2023, 10:52
- Refresh button

The bottom right corner of the map area includes the text "© OpenStreetMap contributors."

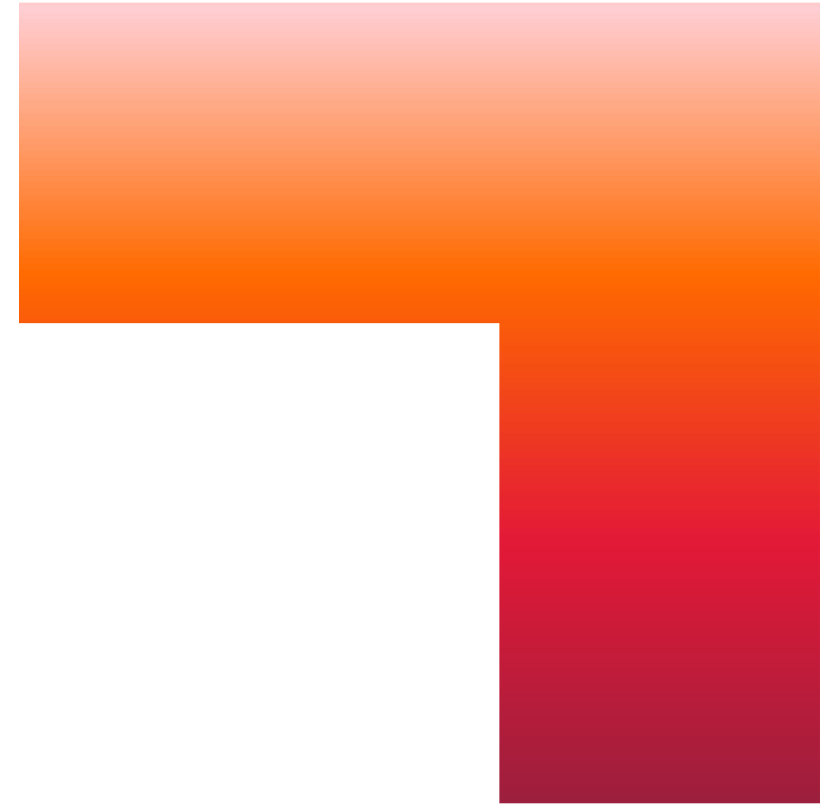


# Insights you can act on

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